



# Design Review Presentation



## **Scientific Shark**

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# Background

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- Prince William Sound, Gulf of Alaska
- Exxon-Valdez Oil Spill (1989)
- Environmental monitoring: Autonomous moored profiler
- Current Problems:
  - Remotely charge battery
  - Data transmission capability
  - Proprietary system

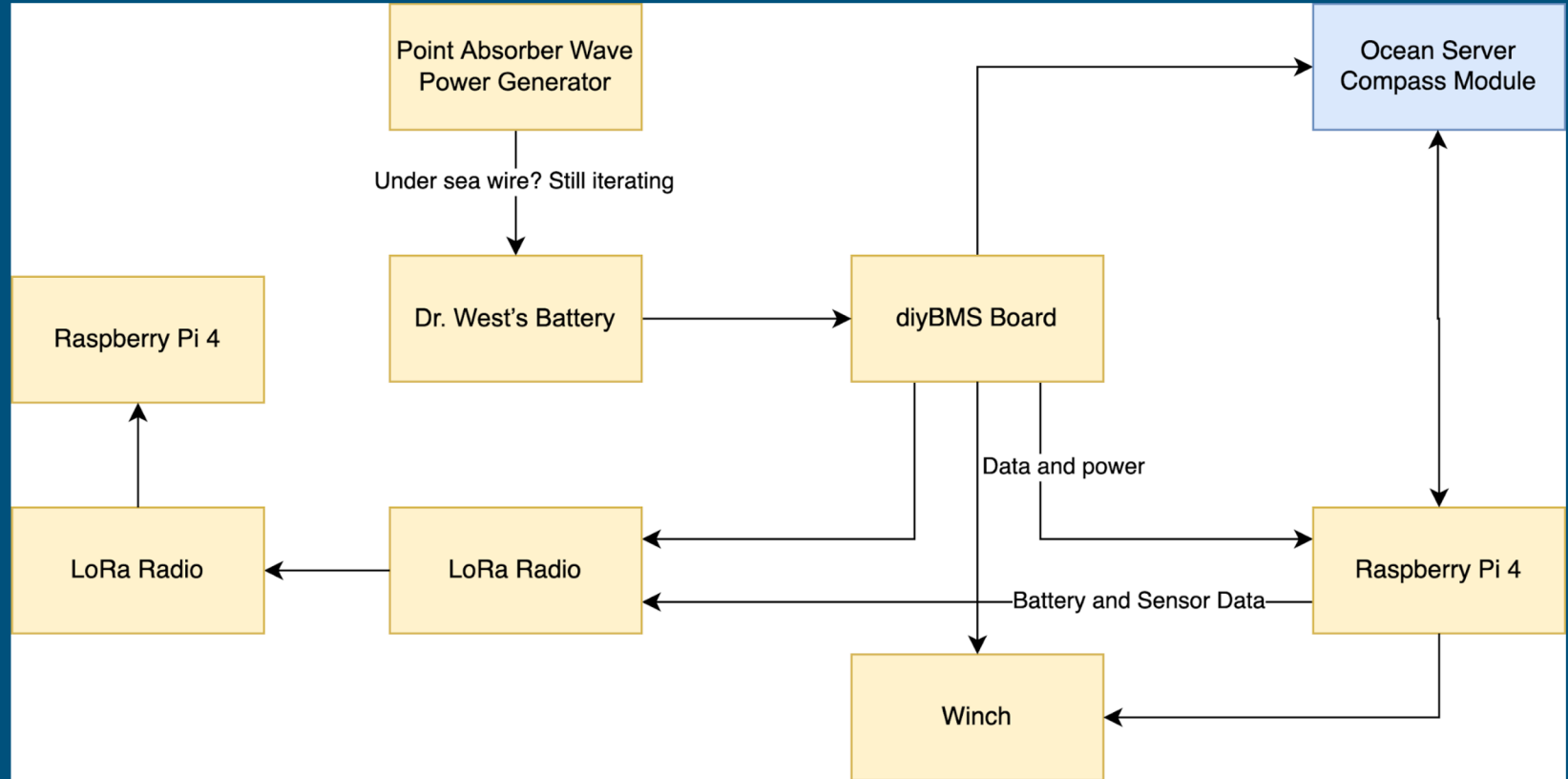


# Agenda

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- High Level Overview of Prototype
- Power Generation
- Battery Communications
- Example Sensor, Compass
- Wireless Communications
- User Interface
- Path to Completion, Schedule
- Cost Analysis

# Block Diagram of Planned Prototype

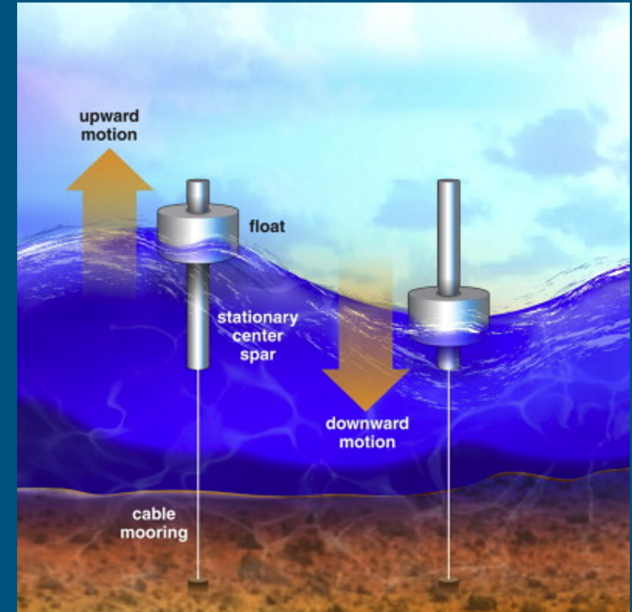




# Power Generator

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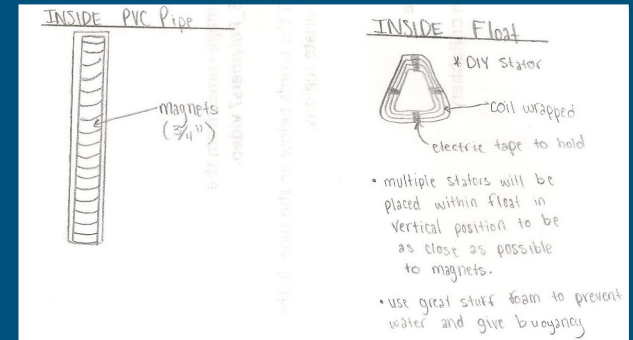
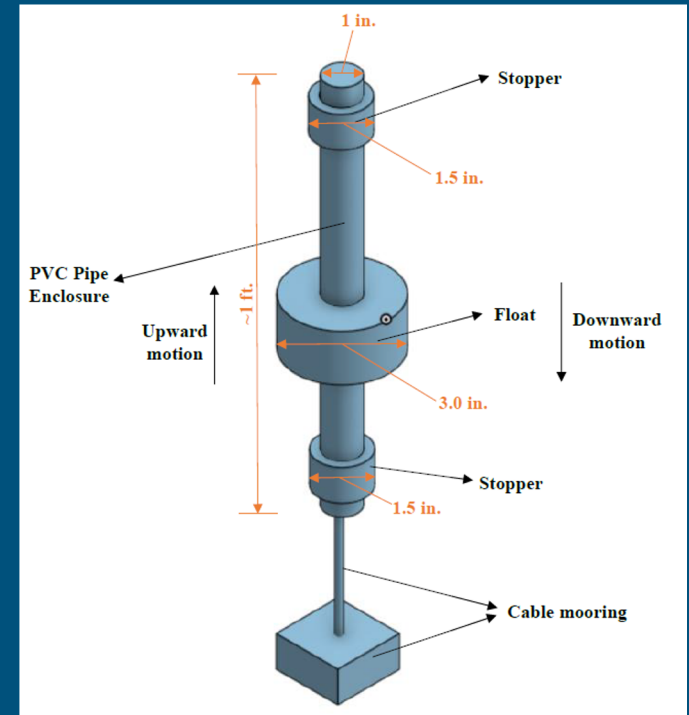
- Point absorber instead of wave attenuator
- Structure
  - Buoy
  - Magnets in the middle tube
  - Stator float moving based on waves
  - Plates (doughnuts) to keep stator in place
  - Mooring to the seabed
- Generator -> Charging system -> Battery



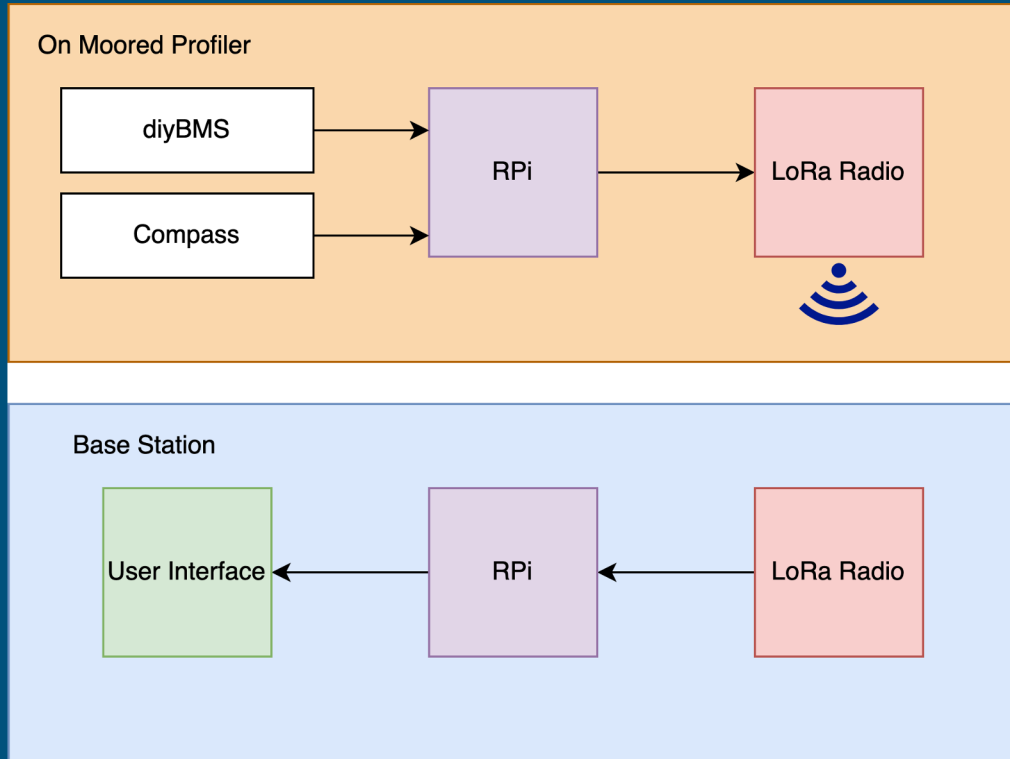
Visual example of point absorber

# Power Generator Visual

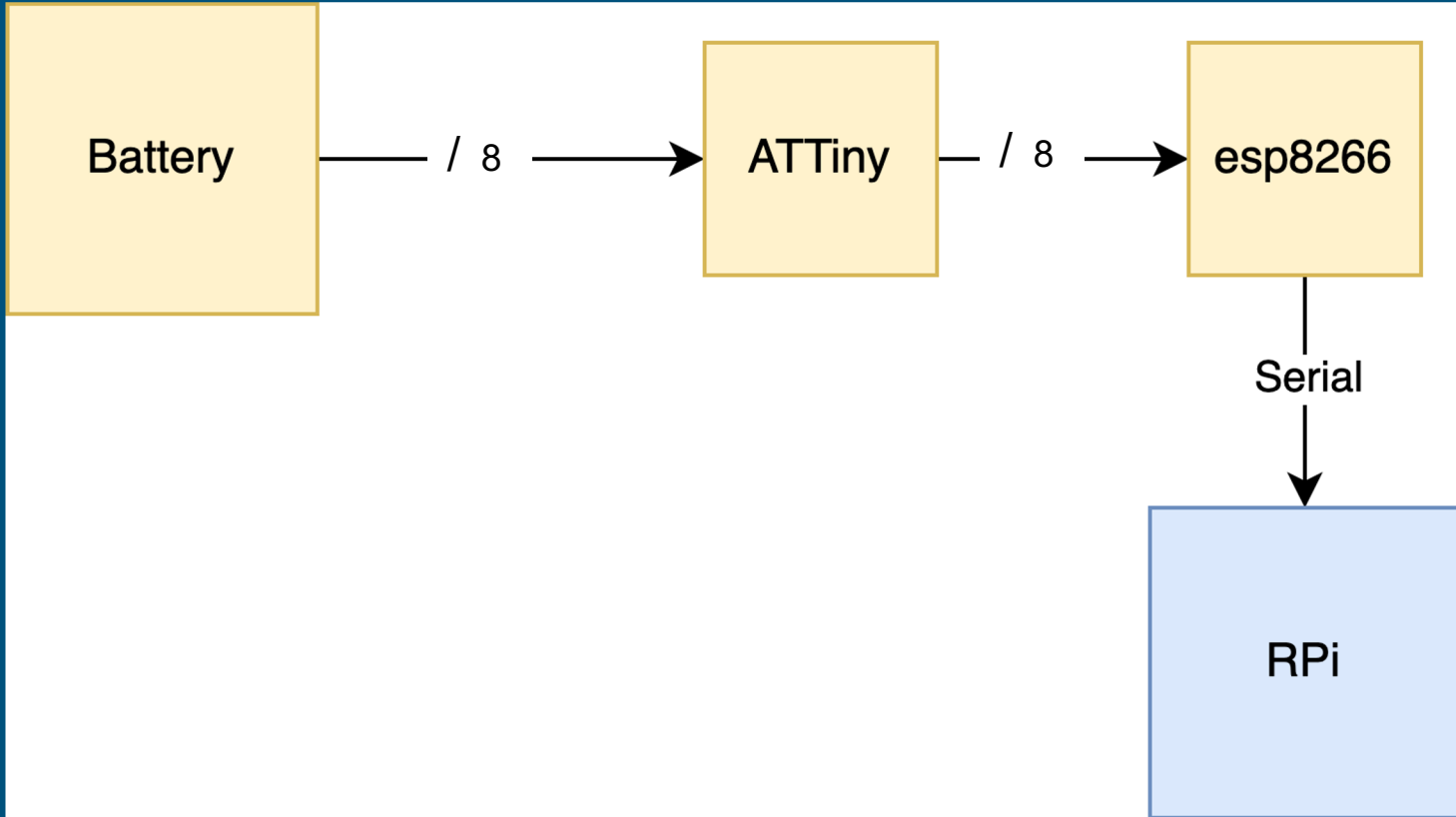
- Inside PVC:
  - Magnets stacked within
- Inside Float:
  - DIY coil stators
- 3D print custom doughnuts and float
- Mooring:
  - Cable and weight



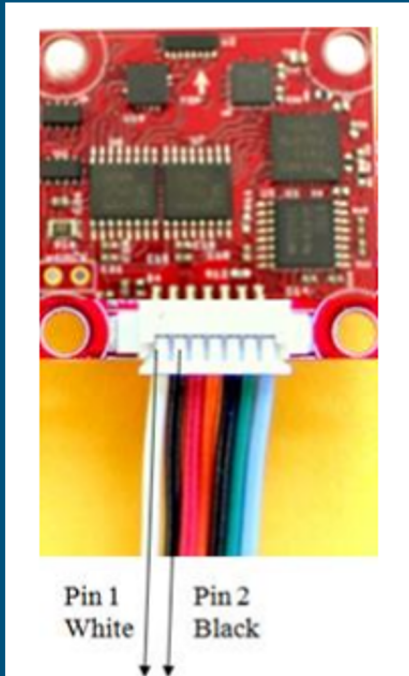
# Software/Hardware Integration



# Battery Communication



# Compass



OS Compass

Order	Bit value (base 10)	Parameter Name
1	1	Azimuth
2	2	Pitch Angle
3	4	Roll Angle
4	8	Temperature
5	16	Depth (feet)
6	32	Magnetic Vector Length
7	64	3 axis Magnetic Field readings, x,y,z
8	128	Acceleration Vector Length
9	256	3 axis Acceleration Readings, x,y,z
10	512	reserved
11	1024	2 axis Gryo Output, X,y (discontinued Part)
12	2048	Reserved
13	4096	Reserved

List of parameters from the compass

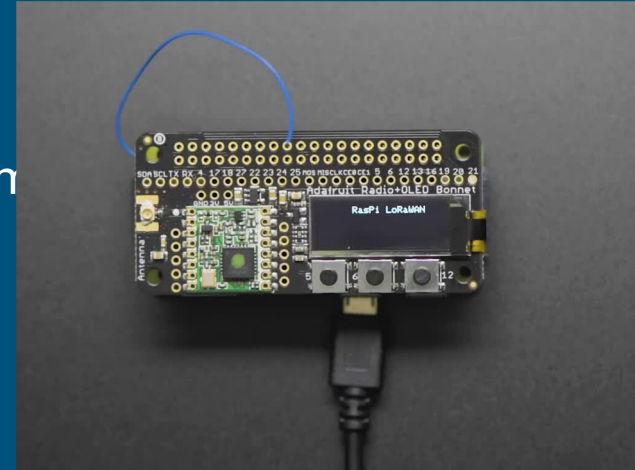
# Radio

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- Long range (LoRa) transmission of packets, low power consumption
- I2C protocol, 915 MHz but can be configured to other frequencies
- Can utilize LoRaWAN (longer distance)

Still need to:

- Send/receive information from battery management system and compass



Adafruit LoRa Radio Bonnet RFM95W

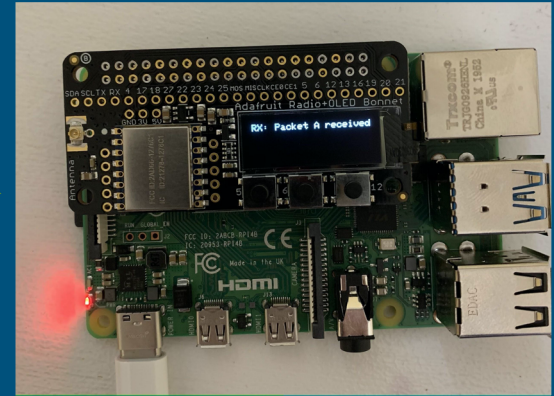
# Radio



Radio 1 sends packet A

~4s

~1km



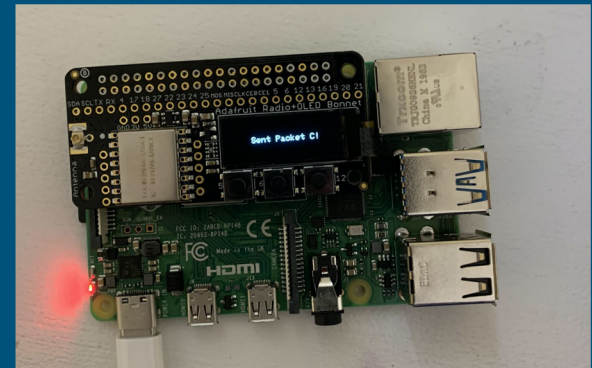
Radio 2 receives packet A

~4s

~1km



Radio 1 receives packet C



Radio 2 sends packet C

# User Interface

Prince William Sound

Profiler Information: Battery Info

Cell 1: ☐ Get Voltage, Current, Temp, Power for Cell 1

Cell 2: ☐ Get Voltage, Current, Temp, Power for Cell 2

Cell 3: ☐ Get Voltage, Current, Temp, Power for Cell 3

Cell 4: ☐ Get Voltage, Current, Temp, Power for Cell 4

Get Data

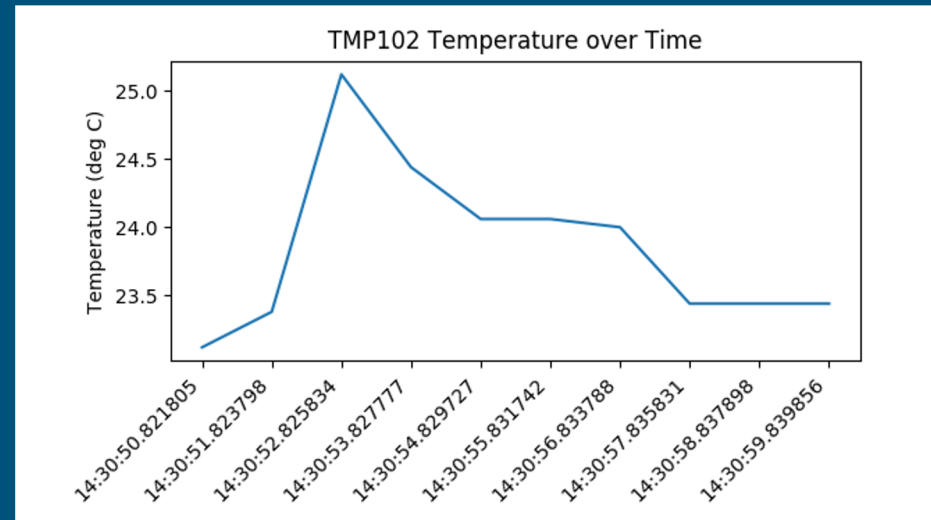
Refresh



Battery Used: 70%.

	Voltage (Volts)	Current(Amps)	Temperature(C)	Power (W)
Cell 1	3.80	4.36	21	100
Cell 2	3.75	5.12	25	205
Cell 3	3.78	8.15	49	125
Cell 4	3.48	7.20	20	198

Current GUI example



Future GUI plans



# Pathway to Success: Schedule

Task Name	Assigned	Days	Start	ETA	19 Oct	26 Oct	2 Nov	9 Nov	16 Nov
					Week 10	Week 11	Week 12	Week 13	Week 14
Iterate on user interface	CompE	23	18 Oct	10 Nov					
Integrate radios, compass, battery communications	CompE	23	18 Oct	10 Nov					
Ordering/waiting for parts	All	7	18 Oct	25 Oct					
Establish serial communications (esp. esp8266)	CompE	7	18 Oct	25 Oct					
Communicate with compass	CompE	8	26 Oct	3 Nov					
Point absorber assembly	EE	7	26 Oct	2 Nov					
Winch Integration	All	7	3 Nov	10 Nov					
Charging system	EE	7	3 Nov	10 Nov					
Finalize expo prototype and presentation	All	8	10 Nov	18 Nov					

# Cost Analysis: Bill of Materials


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Topics	Materials	Quality	Total Price
Power Generator	Magnet	10	\$89.30
	Temflex 3/4 in. x 60 ft. 1700 Electrical Tape Black	1	\$1.78
	Rare Earth 3/4 in. x 1/4 in. Disc Magnet (4-Pack)	1	\$190.42
Battery Communication	Raspberry Pi 4 15W Power Supply	1	\$8.47
Radio Communication	Adafruit LoRa Radio Bonnet with OLED	2	\$80.22
		Total	\$370.19

# Reference

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[https://ocean-server.com/wp-content/uploads/2018/08/OS5000\\_Compass\\_Manual.pdf](https://ocean-server.com/wp-content/uploads/2018/08/OS5000_Compass_Manual.pdf)



Thank You!  
Any Question?